

TABELLA		U5	Davanzo
Innoval	11	47	03115
	12	47	03115
	13	47	03115
	14	127,6	04060
	15	142,9	04060
	16	101,9	04060
	17	101,9	04060
	18	101,9	04060
	19	68,2	04060
	20	68,2	04060
	21	61,9	04060
	22	158,3	04060
	23	119,4	04060
	24	57,3	03000
	25	37,3	03000
	26	57,3	03000

The diagram illustrates the architecture of a multi-agent system for a multi-robot environment. It is divided into three main areas: AREA MANOVA, AREA TUBERLE, and AREA TUBERLE. The MANOVA area contains a central node '1' and two nodes '2' and '3'. The TUBERLE areas contain nodes '4' and '5'. Arrows indicate communication and data flow between these nodes and the central node '1'. The diagram also shows the physical layout of the environment with obstacles and a starting point for the robots.

Diagram 1 (SEZIONE 3-2) shows a cross-section of a ditch with a width of 300 and a depth of 150. The ditch is filled with water to a depth of 100. The water level is marked with a blue line and a blue arrow. The ditch bed is marked with a blue line and a blue arrow. The ditch is flanked by a hatched area representing the ditch bed. The diagram is labeled SEZIONE 3-2 and has a scale of 1:100.

Diagram 2 (SEZIONE 3-3) shows a cross-section of a ditch with a width of 300 and a depth of 150. The ditch is filled with water to a depth of 100. The water level is marked with a blue line and a blue arrow. The ditch bed is marked with a blue line and a blue arrow. The ditch is flanked by a hatched area representing the ditch bed. The diagram is labeled SEZIONE 3-3 and has a scale of 1:100.

Diagram 3 (SEZIONE 3-4) shows a cross-section of a ditch with a width of 300 and a depth of 150. The ditch is filled with water to a depth of 100. The water level is marked with a blue line and a blue arrow. The ditch bed is marked with a blue line and a blue arrow. The ditch is flanked by a hatched area representing the ditch bed. The diagram is labeled SEZIONE 3-4 and has a scale of 1:100.

